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10/822,133	04/09/2004	Kenneth Perlin	NYU-10	2476
7590 08/21/2007			EXAMINER	
Ansel M. Schw	artz		JEN, MINGJEN	
Suite 304 201 N. Craig St	treet		ART UNIT	PAPER NUMBER
Pittsburgh, PA 15213			3609	
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Please find below and/or attached an Office communication concerning this application or proceeding.

The time period for reply, if any, is set in the attached communication.

	Application No.	Applicant(s)		
Office Action Commence	10/822,133	PERLIN ET AL.		
Office Action Summary	Examiner	Art Unit `		
	lan Jen	3609		
The MAILING DATE of this communication appeariod for Reply	ears on the cover sheet with the c	orrespondence address		
A SHORTENED STATUTORY PERIOD FOR REPLY WHICHEVER IS LONGER, FROM THE MAILING DA  - Extensions of time may be available under the provisions of 37 CFR 1.13 after SIX (6) MONTHS from the mailing date of this communication.  - If NO period for reply is specified above, the maximum statutory period with a period for reply within the set or extended period for reply will, by statute, Any reply received by the Office later than three months after the mailing earned patent term adjustment. See 37 CFR 1.704(b).	TE OF THIS COMMUNICATION 6(a). In no event, however, may a reply be tin ill apply and will expire SIX (6) MONTHS from cause the application to become ABANDONE	N. nely filed the mailing date of this communication. D (35 U.S.C. § 133).		
Status				
1) ☐ Responsive to communication(s) filed on ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐	action is non-final. ce except for formal matters, pro			
Disposition of Claims				
4)  Claim(s) 1-15 is/are pending in the application. 4a) Of the above claim(s) is/are withdraw 5)  Claim(s) is/are allowed. 6)  Claim(s) 1-15 is/are rejected. 7)  Claim(s) is/are objected to. 8)  Claim(s) are subject to restriction and/or				
Application Papers				
9) The specification is objected to by the Examiner 10) The drawing(s) filed on 04/09/2004 is/are: a) Applicant may not request that any objection to the d Replacement drawing sheet(s) including the correction 11) The oath or declaration is objected to by the Examiner	accepted or b) objected to by drawing(s) be held in abeyance. See on is required if the drawing(s) is ob	e 37 CFR 1.85(a). ected to. See 37 CFR 1.121(d).		
Priority under 35 U.S.C. § 119				
12) Acknowledgment is made of a claim for foreign pa) All b) Some * c) None of:  1 Certified copies of the priority documents 2 Certified copies of the priority documents 3. Copies of the certified copies of the priori application from the International Bureau	have been received. have been received in Applicati ty documents have been receive (PCT Rule 17.2(a)).	on No ed in this National Stage		
* See the attached detailed Office action for a list of the certified copies not received.				
Attachment(s)  1) Notice of References Cited (PTO-892)  2) Notice of Draftsperson's Patent Drawing Review (PTO-948)  3) Information Disclosure Statement(s) (PTO/SB/08)  Paper No(s)/Mail Date		te		

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#### **DETAILED ACTION**

### Specification

1. The abstract of the disclosure is objected to exceed one hundred fifty words limit.

Correction is required. See MPEP § 608.01(b).

## Claim Rejections - 35 USC § 102

- 2. The following is a quotation of the appropriate paragraphs of 35 U.S.C. 102 that form the basis for the rejections under this section made in this Office action:
  - (e) the invention was described in (1) an application for patent, published under section 122(b), by another filed in the United States before the invention by the applicant for patent or (2) a patent granted on an application for patent by another filed in the United States before the invention by the applicant for patent, except that an international application filed under the treaty defined in section 351(a) shall have the effects for purposes of this subsection of an application filed in the United States only if the international application designated the United States and was published under Article 21(2) of such treaty in the English language.
- 3. Claim 1 is rejected under 35 U.S.C. 102(e) as being anticipated by Hara et al (US Pat N0 7082351).

As for Claim 1, Hara et al shows a system for manipulation of objects comprising(
Abstract): N objects, where N is greater than or equal to 2 and is an integer; and means for
controlling and 2D locating of the N objects (Fig 1, Column 1, lines 59 - Column 2, lines 40;
Column 3, lines 42 - 48).

As for Claim 2, Hara et al shows a system wherein the controlling means includes indicators disposed on the object (Column 38, lines 5-60).

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As for Claim 3, Hara et al shows a system wherein the controlling means includes sensing means for locating the objects (Column 3, lines 42 - 53).

As for Claim 4, Hara et al shows a system wherein position indicators include emitters which indicate a position of an object (Column 38, lines 5 -60; Column 59, lines 20-30).

As for Claim 5, Hara et al shows a system wherein the objects are vehicles (Column 42, lines 61 - Column 43, lines 5 where wheeled robot apparatus moving on the two dimensional plane).

As for Claim 6, Hara et al shows a system wherein the controlling means includes a vehicle controller disposed with each vehicle (Fig 19, Column 25, lines 61 - Column 26, lines 46).

As for Claim 7, Hara et al shows a system wherein the vehicle controller of each vehicle includes an MCU (Column 38, lines 42 - Column 39, lines 2).

As for Claim 8, Hara et al shows a system wherein the sensing means includes sensors (Column 14, lines 49-56).

As for Claim 9, Hara et al a system wherein the emitters include LEDs (Column 46, lines 17-25).

As for Claim 10, Hara et al shows a method for manipulating objects comprising the steps of: receiving information from N objects, where N is greater than or equal to 2 and is an

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integer, at a centrally controlling and 2D locating controller Fig 1, Column 1, lines 59 - Column 2, lines 40; Column 3, lines 42 - 48); determining 2D locations by the controller of the N objects object (Column 38, lines 5 -60; Column 59, lines 20-30); and transmitting from the controller directions to the N objects for the N objects to move (Column 2, lines 12 - 52).

As for Claim 11, Hara et al shows a method as described in claim 10 wherein the transmitting step includes the step of transmitting from the controller kinematic parameters to the N objects (Column 59, lines 16 - 32; Column 55, lines 15 -65).

As for Claim 12, Hara et al shows an apparatus for tracking comprising: N objects, where N is greater than or equal to 2 and is an integer (Fig 1, Column 1, lines 59 - Column 2, lines 40; Column 3, lines 42 - 48), each object having an emitter which emits light; and means for 2D sensing of the N objects over time from the light emitted by each emitter (Column 46, lines 17-25).

As for Claim 13, Hara et al shows an apparatus as described in claim 12 including a planar element on which the N objects are disposed, and wherein the sensing means includes at least 2 1-D sensors that sense the light emitted from the edge of the planar element on which the objects are disposed (Column 42, lines 61 - Column 43, lines 5 where wheeled robot apparatus moving on the two dimensional plane; Column 38, lines 5-60; Column 46, lines 17-25).

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As for Claim 14, Hara et al shows a method for tracking comprising the steps of: emitting light from N objects, where N is greater than or equal to 2 and is an integer; and sensing 2D locations of the N objects over time from the emitted light from the N objects (Fig 1, Column 1, lines 59 - Column 2, lines 40; Column 3, lines 42 - 48; Column 46, lines 17-25).

As for Claim 15, Hara et al show a method as described in claim 14 wherein the sensing step includes the step of sensing 2D locations of the N objects over time from the emitted light from the N objects through an edge of a planar element on which the N objects are disposed(Column 42, lines 61 - Column 43, lines 5 where wheeled robot apparatus moving on the two dimensional plane; Column 38, lines 5-60; Column 46, lines 17-25; Fig 1, Column 1, lines 59 - Column 2, lines 40; Column 3, lines 42 - 48; Column 46, lines 17-25).

#### Conclusion

The prior art made of record and not relied upon is considered pertinent to applicant's disclosure.

Byrne et al (US Pat No 6687571) shows multiple robot apparatus in cooperating with each other. Johannessen et al (US Pat Pub 2004/0148058) shows multiple robot apparatus in cooperating with each other.

Solomon (US Pat Pub 2004/0030449) shows multiple robot apparatus in cooperating with each other.

Any inquiry concerning this communication or earlier communications from the examiner should be directed to Ian Jen whose telephone number is 571-270-3274. The examiner can normally be reached on Monday - Friday 8:00-5:00 (EST).

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If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Khoi Tran can be reached on 571-272-6919. The fax phone number for the

organization where this application or proceeding is assigned is 571-273-8300.

Information regarding the status of an application may be obtained from the Patent

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information system, call 800-786-9199 (IN USA OR CANADA) or 571-272-1000.

Ian Jen 17/08-2007 Ian Jen

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